

HK450

Channel 1: **Front Left servo**
Channel 2: **Rear servo**
Channel 3: **Throttle**
Channel 4: **Tail servo**
Channel 5: **Not connected**
Channel 6: **Front Right servo**

Model Type: **Heli 120**
Stick Type: **Mode 2**

Normal/Reverse	End Point	Throttle (Normal/Idle)		Pitch (Normal/Idle)	
Channel 1: N	Channel 1: 100 100	P1: 0	70	P1: 20	20
Channel 2: N	Channel 2: 100 100	P2: 30	70	P2: 55	55
Channel 3: R	Channel 3: 100 100	P3: 65	70	P3: 62	62
Channel 4: N	Channel 4: 50 50	P4: 80	80	P4: 85	85
Channel 5: R	Channel 5: 100 100	P5: 90	90	P5: 100	100
Channel 6: R	Channel 6: 100 100				

Swash AFR	Dual Rate (On/Off)		SubTrim	
Channel 1: 50	Channel 1: 100 50	Channel 1: 90	Channel 4: 5	
Channel 2: -50	Channel 2: 100 50	Channel 2: 90	Channel 5: 0	
Channel 6: -70	Channel 4: 100 50	Channel 3: 0	Channel 6: 60	

Switch	Variable
Switch a: Normal/Idle	Variable a: Null
Switch b: Throttle Cut	Variable b: Pitch Adjust

Mix 1		Mix 2		Mix 3	
Source	Channel 1	Source	Channel 1	Source	Channel 1
Destination	Channel 2	Destination	Channel 2	Destination	Channel 2
Up Rate	0	Up Rate	0	Up Rate	0
Down Rate	0	Down Rate	0	Down Rate	0
Switch	Off	Switch	Off	Switch	Off

Notes

HXT 900 as cyclic servos, HXT 500 as tail servo, KD KA450H 3200kv motor

Telebee GR302-AD as gyro